# Optimizing Probes of New Physics Models

Generative Algorithm-Driven Nested Sampling for Parameter Estimation

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From Big Bang to Now: A Theory-Experiment Dialogue SRM University-AP

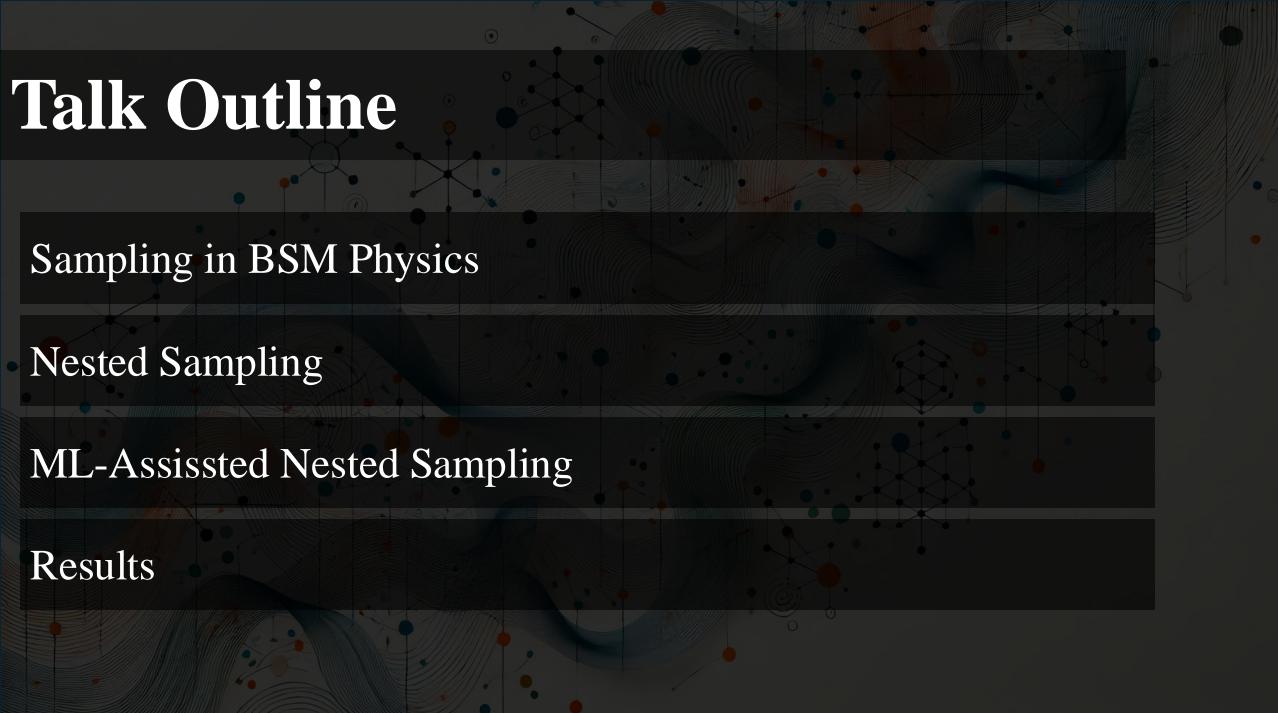
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Preliminary Results of a work in progress 2501.xxxxxx hep-ph

#### **Collaborators:**

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#### **BSM Physics**

New physics (NP) models are 'Physics Inspired'

Standard Model (SM) provides highly accurate and experimentally validated predictions.

NP models have limited parameter space available.

Assessing the statistical consistency of new physics models is critical.

### Sampling High-Dimensional Space

Curse of Dimensionality: Space Volume grows exponentially. Makes uniform sampling expensive.

Sparse Data Distribution: Have most points far from each other

Complex Landscapes: Often have multiple local minima, complicating efficient exploration.

Computational Cost: Evaluating functions or models for high-dimensional inputs is resource-intensive.

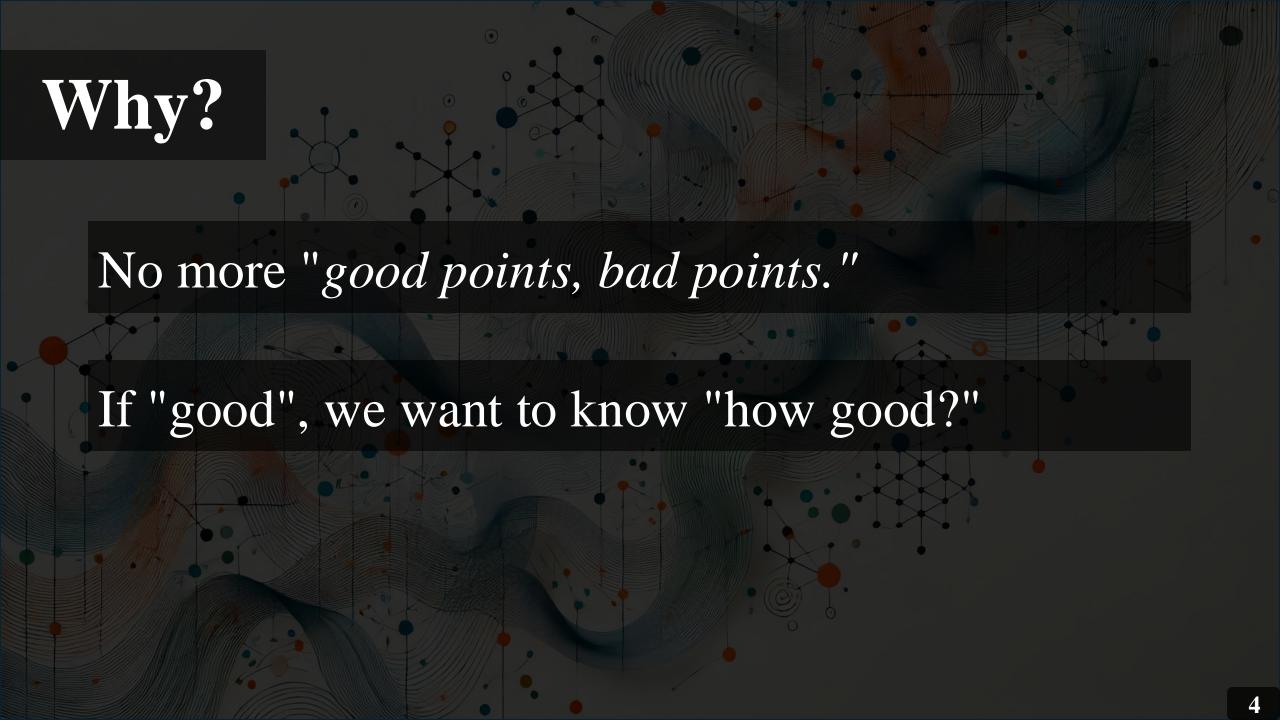
#### Bayes' Theorem

Likelihood Function

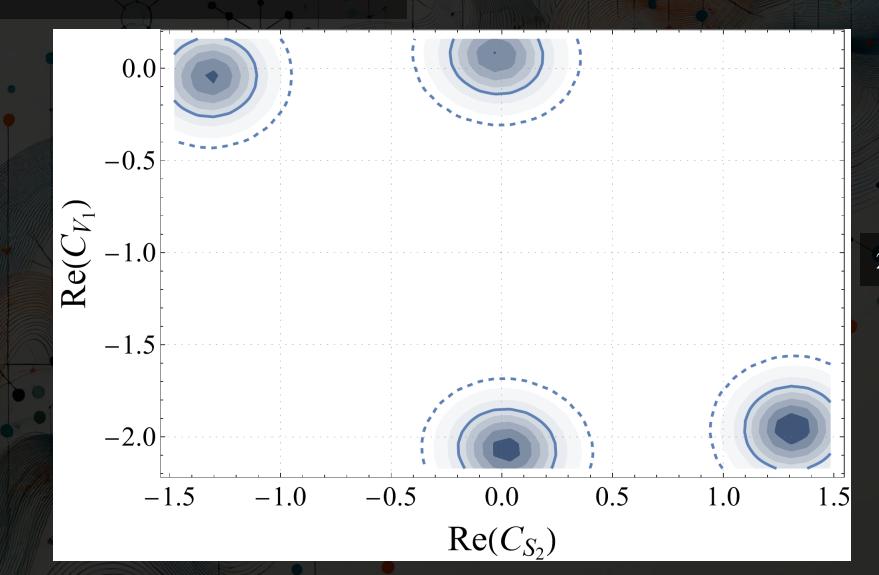
Prior Distribution

$$P(B_{J} | A) = \frac{P(A | B_{J})P(B_{J})}{\sum_{i=1}^{n} P(A | B_{i})P(B_{i})}$$

**Evidence** 



### MCMC



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Nested Sampling is a powerful algorithm for calculating *Bayesian Evidence* and exploring *posterior distributions*.

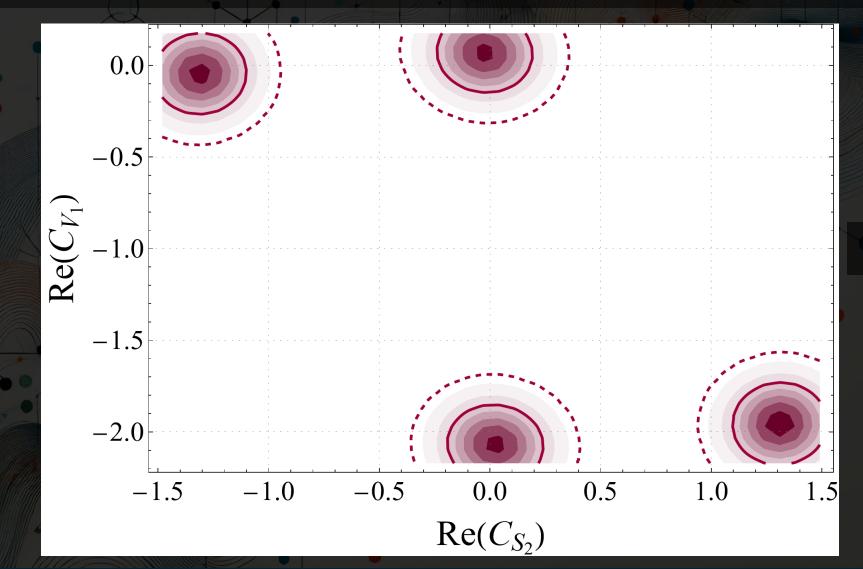
Simultaneous Z calculation for model comparison and parameter inference, unlike classical MCMC.

Effective in multi-modal problems, sampling entire prior space, capturing all modes.

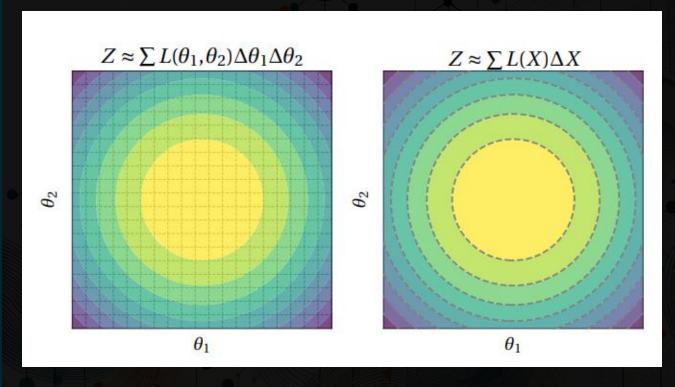
Self-tuning with minimal monitoring, easy application to new problems.

Parallelizable: Combine runs for higher precision, addressing MCMC limitations.

## Nested Sampling Result



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Compression,  $t \sim \beta(n_{\text{live}}, 1)$ 0.0

0.5 X

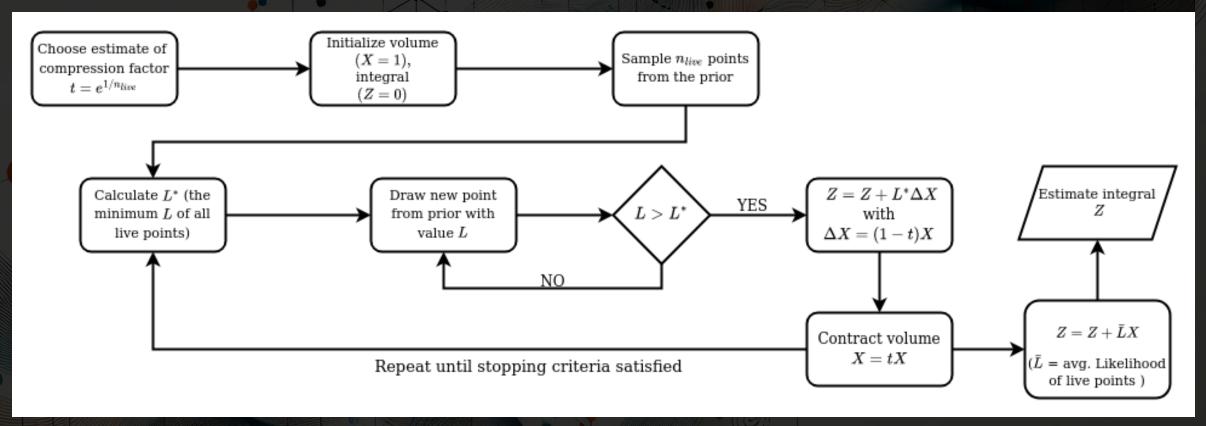
Uniformly distributed live points

Remove worst

Draw replacement

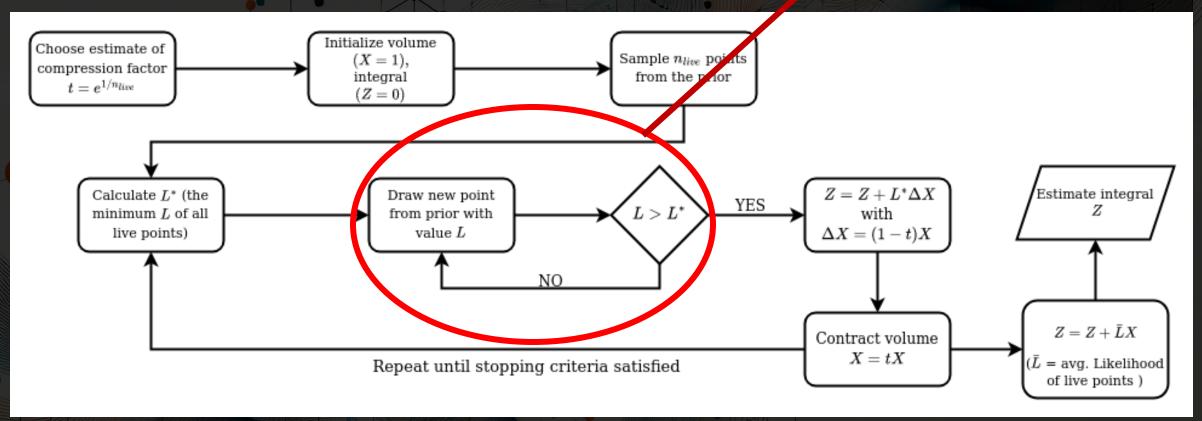
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#### Extremely Time Inefficient

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#### Generative Algorithms

Algorithms that generate new data samples resembling a given dataset, such as images, text, or audio.

**Examples**: Variational Autoencoders (VAEs), Generative Adversarial Networks (GANs), and Diffusion Models.

**Applications**: Image synthesis, text generation, drug discovery, and data augmentation.

Challenges: Balancing realism and diversity, computational cost, and mitigating biases in generated outputs.

#### Normalizing Flows

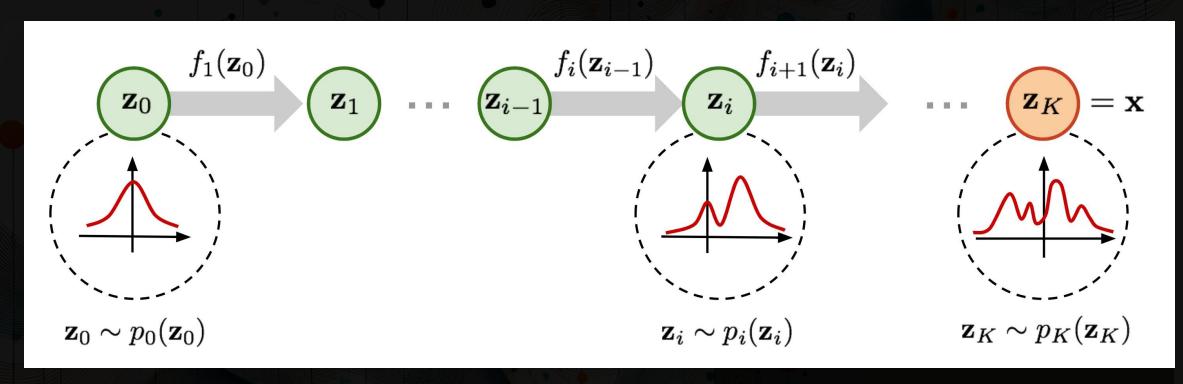
Designed to transform a simple probability distribution into a more complex target distribution: sequence of invertible and differentiable transformations.

Generates realistic samples by sampling from the simple base distribution and applying the learned transformations.

Used in tasks requiring high-quality density estimation or likelihood-based generation.

Normalizing flows use a **deterministic and invertible mapping** to learn the data distribution explicitly.

#### ML-Assisted NS



https://ankurdhuriya.medium.com/

#### How do we make use of it?

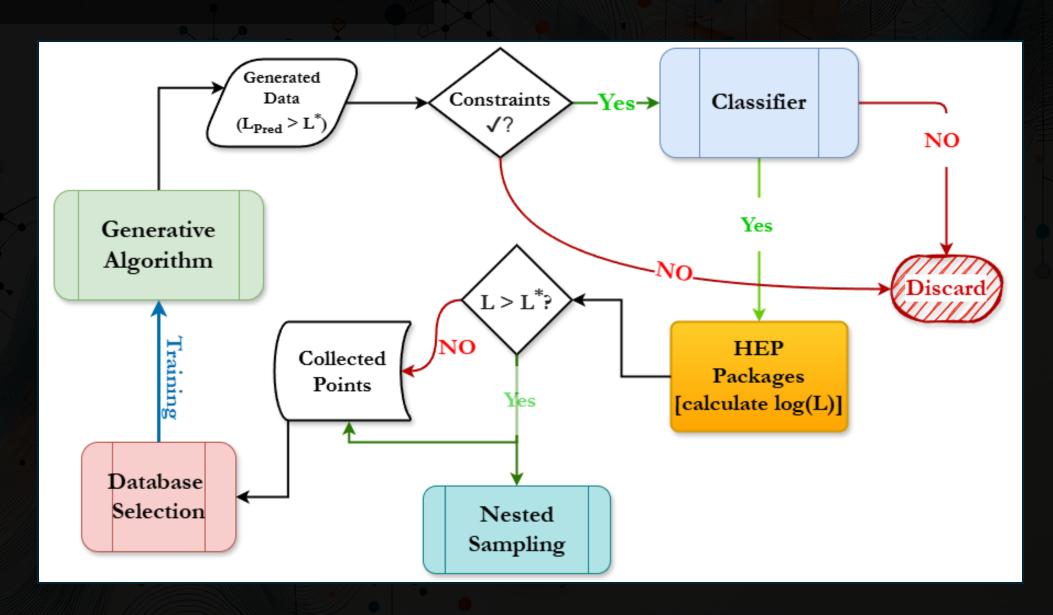
Likelihood Calculation is a Time Inefficient task.

We sample a training dataset consisting of parameters, observables, and chi-square values.

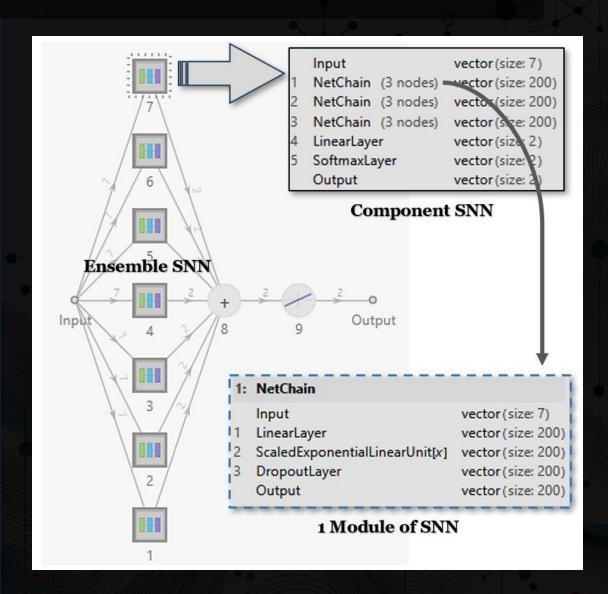
Train a generative algorithm to learn the distribution of the dataset.

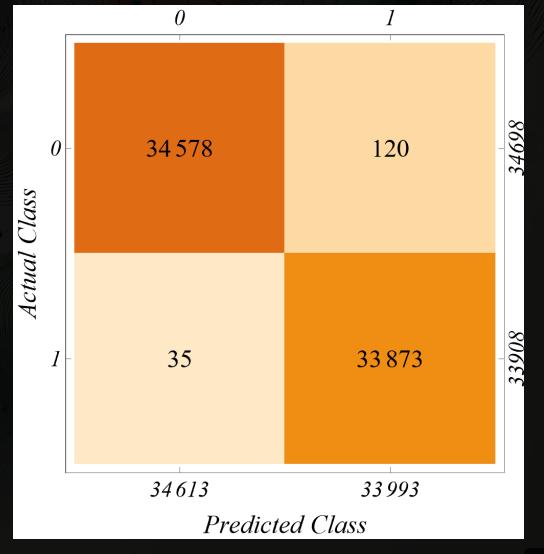
During Nested Sample, we sample from this new *Learned Distribution* rather than the prior itself.

#### ML-Assisted NS



#### Classifier



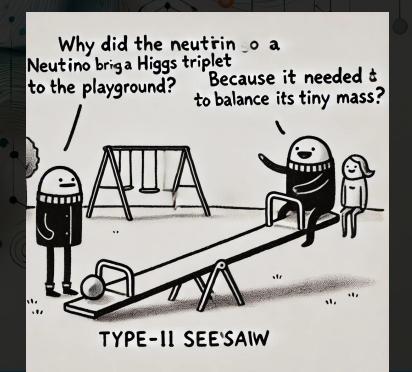


#### Type-II Seesaw Model

$$V(H,\Delta) = -m_H^2 H^{\dagger} H + \frac{\lambda}{4} (H^{\dagger} H)^2 + M_{\Delta}^2 Tr(\Delta^{\dagger} \Delta) + \left[ \mu (H^T i \sigma^2 \Delta^{\dagger} H) + \text{h.c.} \right]$$
$$+ \lambda_1 (H^{\dagger} H) Tr(\Delta^{\dagger} \Delta) + \lambda_2 (Tr \Delta^{\dagger} \Delta)^2 + \lambda_3 Tr(\Delta^{\dagger} \Delta)^2 + \lambda_4 H^{\dagger} \Delta \Delta^{\dagger} H$$

Extends the SM by introducing a scalar triplet

Explains Neutrino Mass through a Majorna Mass term leading to Lepton Number Violation



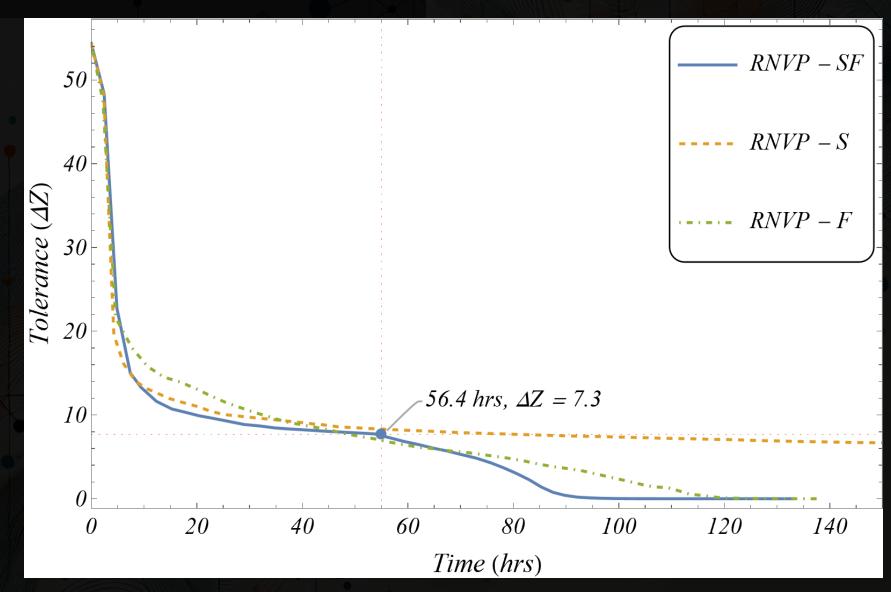
#### Real NVP - S/F/SF

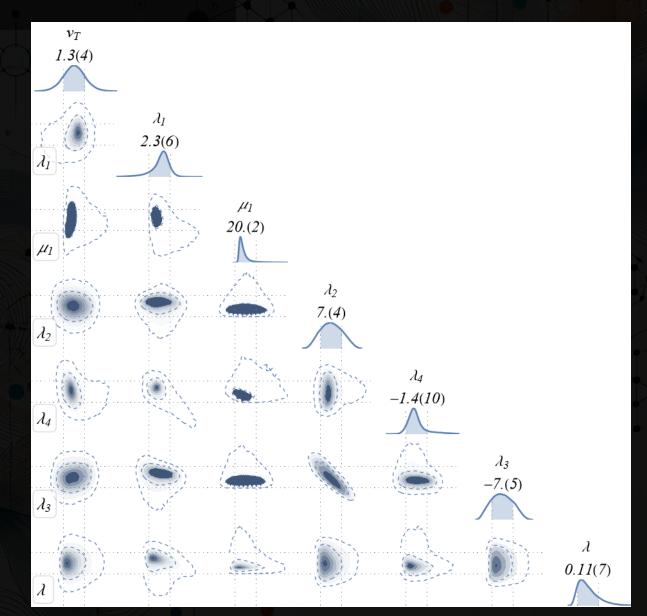
RealNVP-S: Pick a Representative Sample from the pool of collected points.

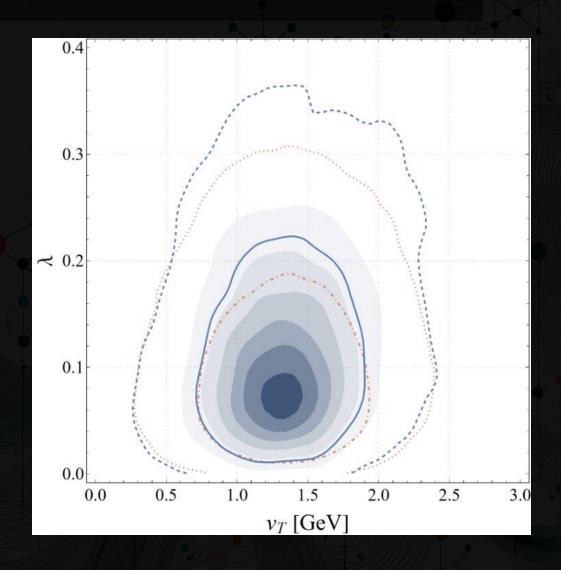
RealNVP-F: Pick sample with *iso-likelihood* contour slightly larger than the one of live points

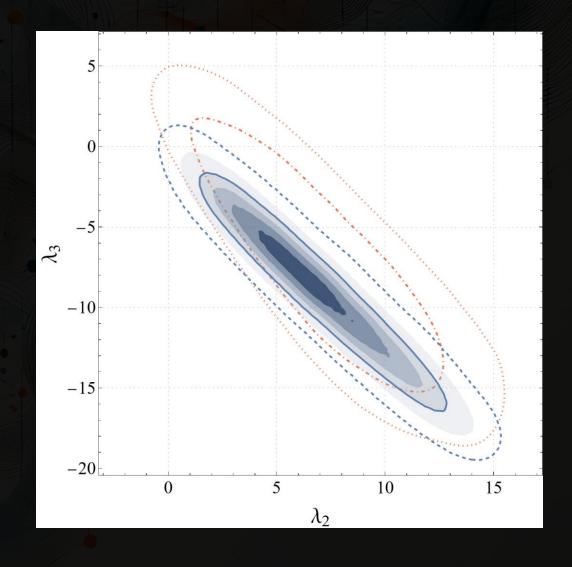
RealNVP-SF – Start with RNVP-S and after saturation, RNVP-F

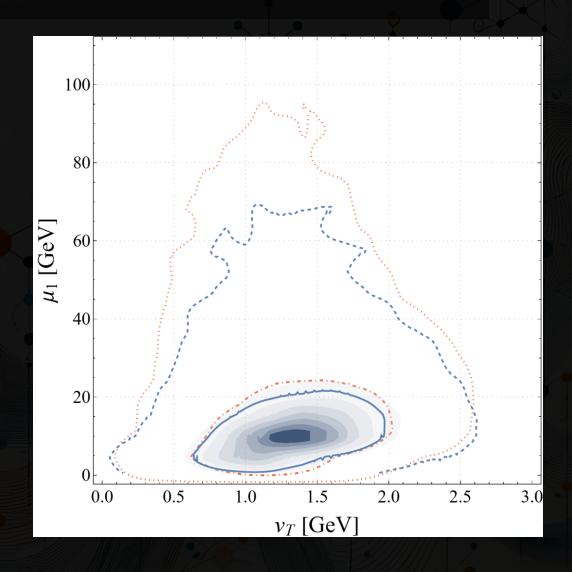
#### **Computation Time**

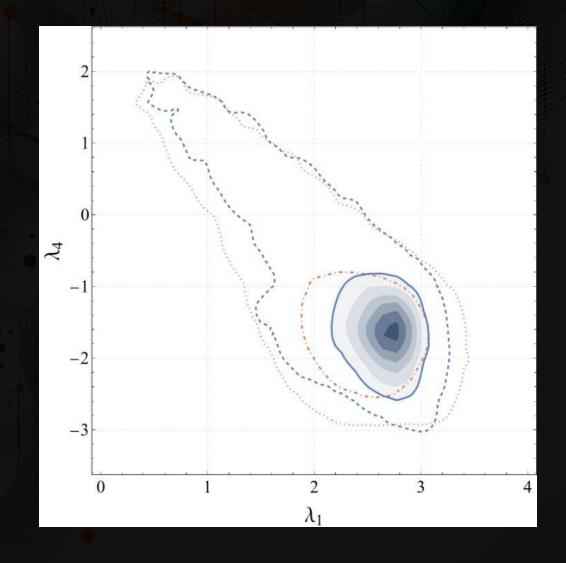


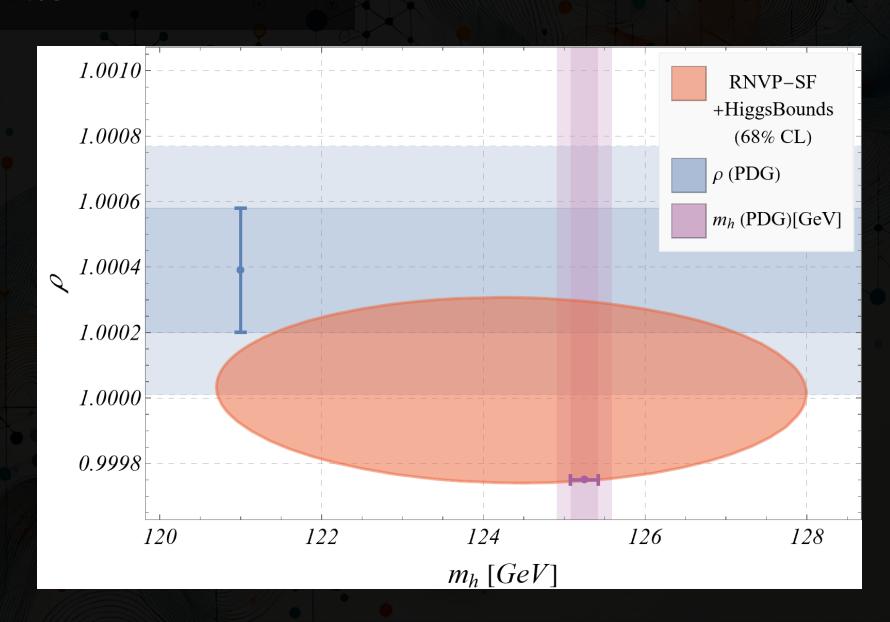


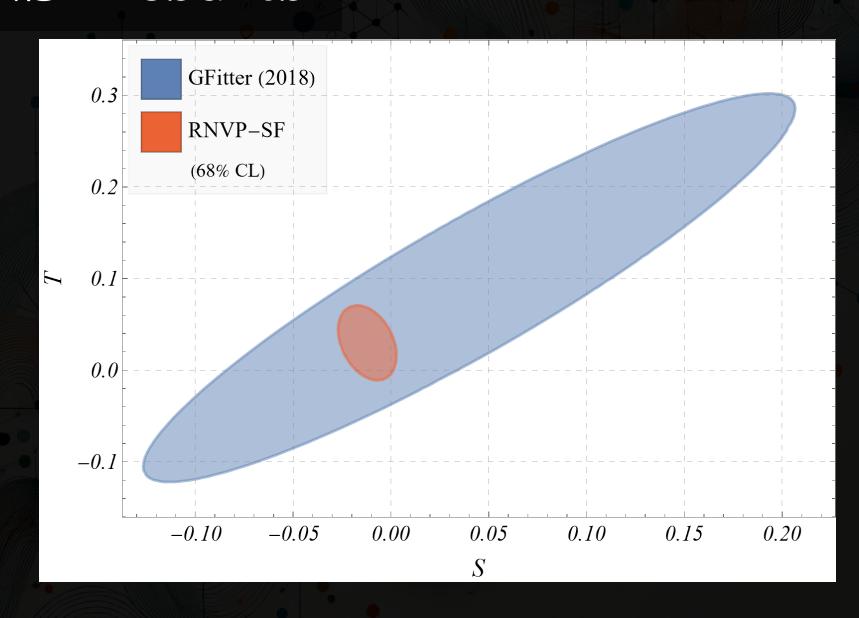












#### Conclusion

Sampling BSM spaces with high-dimensional parameter spaces is difficult.

Standard MCMC and NS have their own flaws.

Using generative algorithms to <u>assist</u> NS makes the algorithm faster.

ML-NS overcomes this and samples the space accurately and in much lesser time.

### Thank You

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